

CLAIMS

1. Method for real-time control of the fabrication of a thin-film structure comprising a substrate by ellipsometric measurement in which:
  - variables directly linked to the ellipsometric ratio  $\rho = \tan\Psi \exp(i\Delta)$  are measured; and
  - the said variables are compared with reference values,characterized in that the comparison relates to the length of the path traveled at a time  $t$  in the plane of the variables with respect to an initial point at time  $t_0$ , for each layer participating in the thin-film structure.
2. Control method according to Claim 1, characterized in that the said variables are a combination of the parameters  $\Psi$  and  $\Delta$ .
3. Control method according to Claim 1, characterized in that the said variables are a combination of trigonometric functions of the parameters  $\Psi$  and  $\Delta$ .
4. Control method according to one of Claims 1 to 3, characterized in that the ellipsometric measurement is one with phase modulation.
5. Control method according to Claim 4, characterized in that the measured variables are, respectively:
$$I_s = (\sin 2\Psi \sin \Delta) \text{ and}$$
$$I_c = (\sin 2\Psi \cos \Delta) \text{ or } I_c = \cos 2\Psi.$$
6. Control method according to one of Claims 1 to 3, characterized in that the ellipsometric measurement is carried out using the method called "rotating polarizer" method.

7. Control method according to Claim 6, characterized in that the measured variables are  $\tan \Psi$  and  $\cos \Delta$ .
- 5 8. Control method according to any one of Claims 1 to 7, characterized in that the ellipsometric measurement is a multiwavelength measurement.
9. Control method according to any one of Claims 1 to 10 8, characterized in that the reference values form a theoretically determined path.
10. Control method according to any one of Claims 1 to 8, characterized in that the reference values form 15 an experimentally determined path.
11. Control method according to any one of Claims 1 to 10, characterized in that the reference values are discrete points corresponding to the instants of 20 fabrication of the thin layers with respect to the time  $t_0$ .
12. Control method according to any one of Claims 1 to 11, characterized in that the path traveled is 25 adjusted by a polynomial of order between 1 and 5.
13. Control method according to any one of Claims 1 to 12, characterized in that the reference values are determined by measurement, using the succession of 30 the following steps:
  - measurement of a known layer on a simple substrate;
  - measurement of the same known layer on an industrial substrate;
  - 35 - measurement of the thin-film structure to be controlled.